

# Abstract Data Types

CS 214, Fall 2019

# What is an ADT?

An ADT defines:

- A set of (abstract) values
- A set of (abstract) operations on those values

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- A set of (abstract) operations on those values

An ADT omits:

- How the values are concretely represented
- How the operations work

## ADT: Stack

Looks like:  $\boxed{3, 4, 5}$

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Signature:

- *push*(Stack, Element)
- *pop*(Stack): Element
- *empty?*(Stack): Bool

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Signature:

- *push*(Stack, Element)
- *pop*(Stack): Element
- *empty?*(Stack): Bool

**interface** STACK:

```
def push(self, element)
def pop(self)
def empty?(self)
```

## Stack Interface, with Contracts

Looks like:  $|3, 4, 5\rangle$

Signature:

```
interface INT_STACK:  
  def push(self, element: int?) -> NoneC  
  def pop(self) -> int?  
  def empty?(self) -> bool?
```

## Stack Interface, with Contracts

Looks like:  $|3, 4, 5\rangle$

Signature:

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interface INT_STACK:  
  def push(self, element: int?) -> NoneC  
  def pop(self) -> int?  
  def empty?(self) -> bool?
```

```
interface STACK[T]:  
  def push(self, element: T) -> NoneC  
  def pop(self) -> T  
  def empty?(self) -> bool?
```



## ADT: Queue (FIFO)

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Looks like: ⟨3, 4, 5⟨

```
interface QUEUE[T]:  
  def enqueue(self, element: T) -> NoneC  
  def dequeue(self) -> T  
  def empty?(self) -> bool?
```

# Stack versus Queue

```
interface STACK[T]:  
  def push(self, element: T) -> NoneC  
  def pop(self) -> T  
  def empty?(self) -> bool?
```

```
interface QUEUE[T]:  
  def enqueue(self, element: T) -> NoneC  
  def dequeue(self) -> T  
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```

## Adding laws

$$\{p\} f(x) \Rightarrow y \{q\}$$

means that if precondition  $p$  is true when we apply  $f$  to  $x$  then we will get  $y$  as a result, and postcondition  $q$  will be true afterward.

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Examples:

$$\{a = [2, 4, 6, 8]\} a[2] \Rightarrow 6 \{a = [2, 4, 6, 8]\}$$

$$\{a = [2, 4, 6, 8]\} a[2] = 19 \Rightarrow \text{None} \{a = [2, 4, 19, 8]\}$$

## ADT: Stack

Looks like:  $|3, 4, 5\rangle$

Signature:

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interface STACK[T]:  
  def push(self, element: T) -> NoneC  
  def pop(self) -> T  
  def empty?(self) -> bool?
```

Laws:

$$\{ \} \quad | \rangle .empty?() \Rightarrow \text{True} \quad \{ \}$$

$$\{ |e_1, \dots, e_k, e_{k+1}\rangle .empty?() \Rightarrow \text{False} \}$$

$$\{ s = |e_1, \dots, e_k\rangle \} \quad s.push(e) \Rightarrow \text{None} \quad \{ s = |e_1, \dots, e_k, e\rangle \}$$

$$\{ s = |e_1, \dots, e_k, e_{k+1}\rangle \} \quad s.pop() \Rightarrow e_{k+1} \quad \{ s = |e_1, \dots, e_k\rangle \}$$

## ADT: Queue (FIFO)

Looks like:  $\langle 3, 4, 5 \langle$

Signature:

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interface QUEUE[T]:  
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$$\{ q = \langle e_1, \dots, e_k \langle \} \quad q.enqueue(e) \Rightarrow \text{None} \quad \{ q = \langle e_1, \dots, e_k, e \langle \}$$
$$\{ q = \langle e_1, e_2, \dots, e_k \langle \} \quad q.dequeue() \Rightarrow e_1 \quad \{ q = \langle e_2, \dots, e_k \langle \}$$

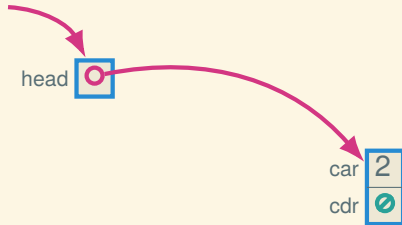
# Stack implementation: linked list



```
let s = ListStack()
```

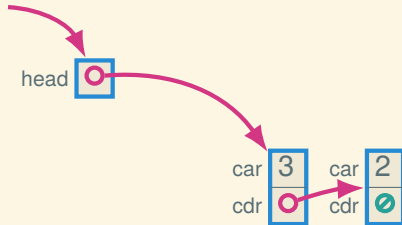


# Stack implementation: linked list



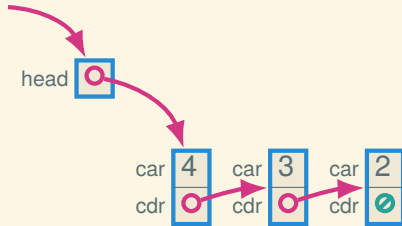
```
let s = ListStack()  
s.push(2)
```

# Stack implementation: linked list



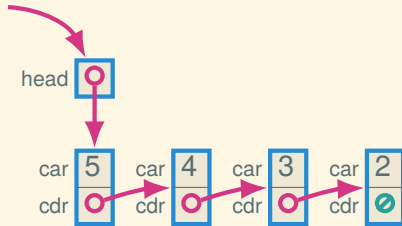
```
let s = ListStack()  
s.push(2)  
s.push(3)
```

# Stack implementation: linked list



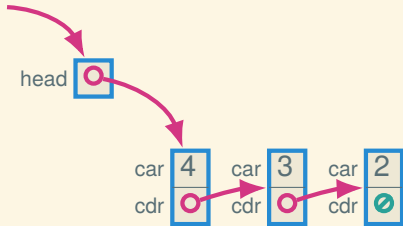
```
let s = ListStack()  
s.push(2)  
s.push(3)  
s.push(4)
```

# Stack implementation: linked list



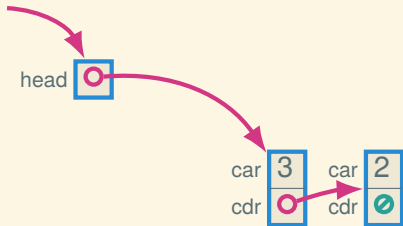
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let s = ListStack()  
s.push(2)  
s.push(3)  
s.push(4)  
s.push(5)
```

# Stack implementation: linked list



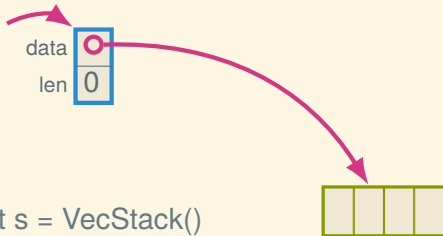
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let s = ListStack()  
s.push(2)  
s.push(3)  
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s.push(5)  
s.pop()
```

# Stack implementation: linked list

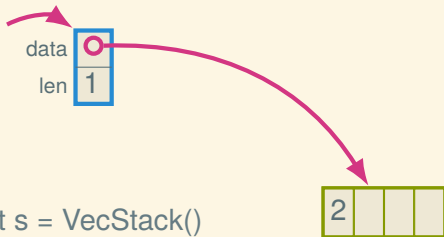


```
let s = ListStack()  
s.push(2)  
s.push(3)  
s.push(4)  
s.push(5)  
s.pop()  
s.pop()
```

# Stack implementation: array



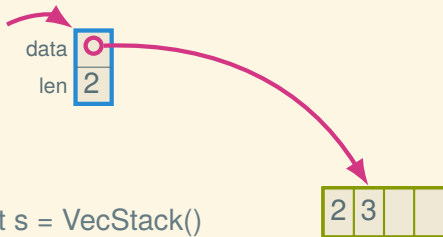
# Stack implementation: array



```
let s = VecStack()  
s.push(2)
```

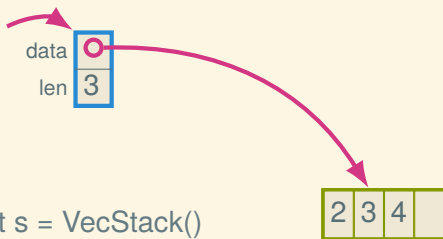


# Stack implementation: array



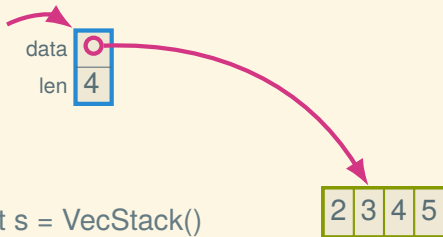
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let s = VecStack()  
s.push(2)  
s.push(3)
```

# Stack implementation: array



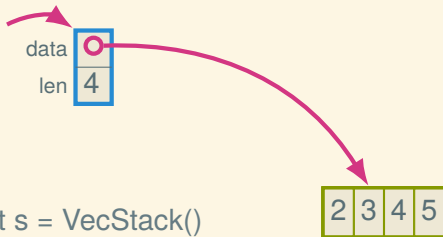
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let s = VecStack()  
s.push(2)  
s.push(3)  
s.push(4)
```

# Stack implementation: array



```
let s = VecStack()  
s.push(2)  
s.push(3)  
s.push(4)  
s.push(5)
```

# Stack implementation: array



```
let s = VecStack()  
s.push(2)  
s.push(3)  
s.push(4)  
s.push(5)  
s.push(6)
```

## ADT: Stack

Looks like:  $|3, 4, 5\rangle$

Signature:

```
interface STACK[T]:  
  def push(self, element: T) -> NoneC # 0(1)  
  def pop(self) -> T # 0(1)  
  def empty?(self) -> bool? # 0(1)
```

Laws:

$$\{ \} \quad | \rangle . \text{empty?}() \Rightarrow \text{True} \quad \{ \}$$

$$\{ \} \quad | e_1, \dots, e_k, e_{k+1} \rangle . \text{empty?}() \Rightarrow \text{False} \quad \{ \}$$

$$\{ s = | e_1, \dots, e_k \rangle \} \quad s . \text{push}(e) \Rightarrow \text{None} \quad \{ s = | e_1, \dots, e_k, e \rangle \}$$

$$\{ s = | e_1, \dots, e_k, e_{k+1} \rangle \} \quad s . \text{pop}() \Rightarrow e_{k+1} \quad \{ s = | e_1, \dots, e_k \rangle \}$$

## Trade-offs: linked list stack versus array stack

- Linked list stack only fills up when memory fills up, whereas array stack has a fixed size (or must reallocate)
- Array stack has better constant factors: cache locality and no (or rare) allocation
- Array stack space usage is tighter; linked list is smoother

## ADT: Queue (FIFO)

Looks like:  $\langle 3, 4, 5 \langle$

Signature:

```
interface QUEUE[T]:  
  def enqueue(self, element: T) -> NoneC # 0(1)  
  def dequeue(self) -> T # 0(1)  
  def empty?(self) -> bool? # 0(1)
```

Laws:

$$\{ \} \quad \langle \langle \rangle .empty?() \Rightarrow \text{True} \{ \}$$
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$$\{ q = \langle e_1, \dots, e_k \langle \} \quad q.enqueue(e) \Rightarrow \text{None} \quad \{ q = \langle e_1, \dots, e_k, e \langle \}$$
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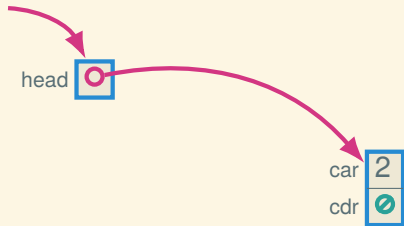
## Queue implementation: linked list?



```
let q = LinkedListQueue()
```

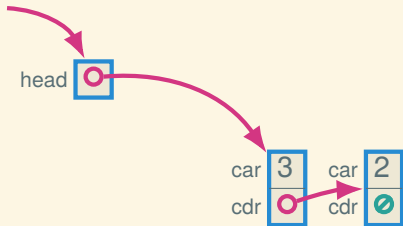


## Queue implementation: linked list?



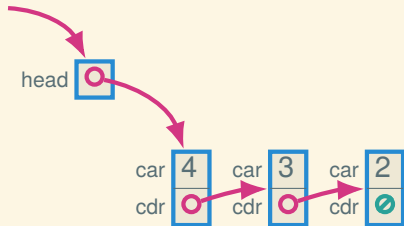
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q.enqueue(2)
```

## Queue implementation: linked list?



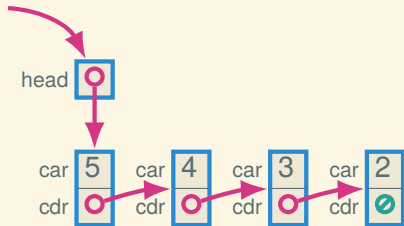
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let q = LinkedListQueue()  
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```

## Queue implementation: linked list?



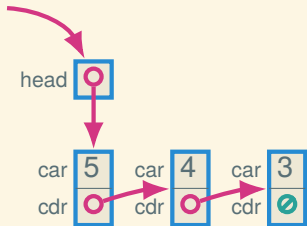
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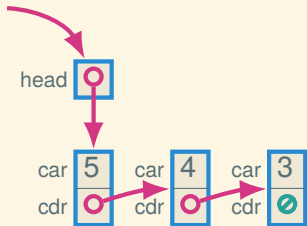
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## Queue implementation: linked list?



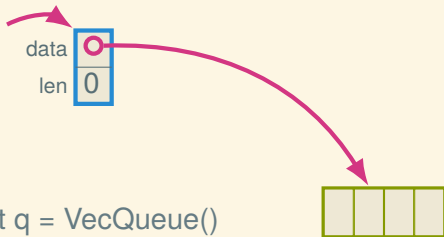
```
let q = LinkedListQueue()  
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q.dequeue()
```

## Queue implementation: linked list?

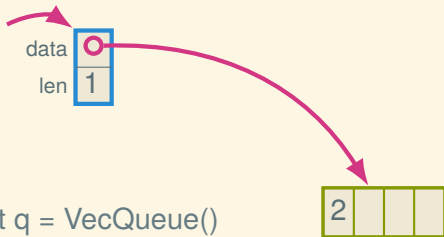


```
let q = LinkedListQueue()  
q.enqueue(2)  
q.enqueue(3)  
q.enqueue(4)  
q.enqueue(5)  
q.dequeue() —  $\mathcal{O}(n)$ ???
```

# Queue implementation: array?



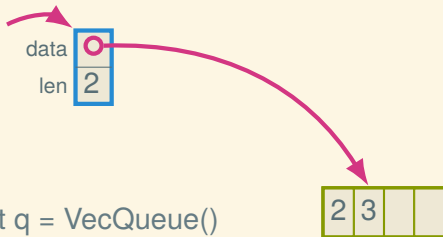
# Queue implementation: array?



```
let q = VecQueue()  
q.enqueue(2)
```

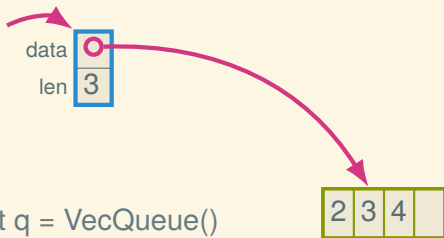


## Queue implementation: array?



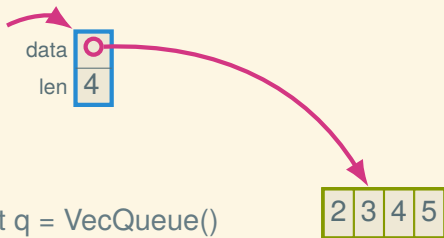
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let q = VecQueue()  
q.enqueue(2)  
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## Queue implementation: array?



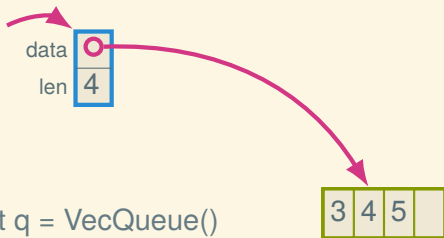
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let q = VecQueue()  
q.enqueue(2)  
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```

## Queue implementation: array?



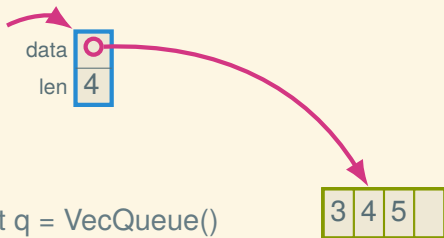
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## Queue implementation: array?



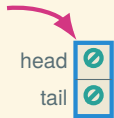
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## Queue implementation: array?



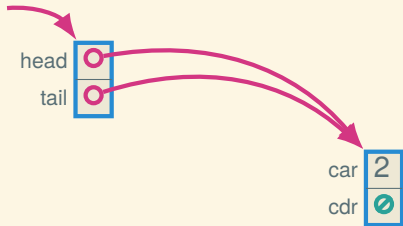
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q.enqueue(2)  
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q.dequeue() —  $\mathcal{O}(n)$ ???
```

## Queue impl.: linked list with tail pointer



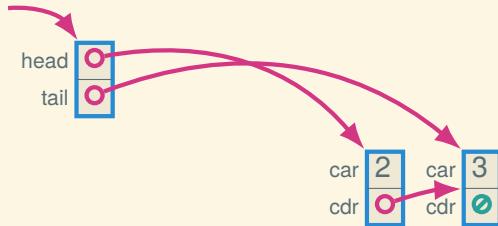
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let q = LinkedListQueue()
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## Queue impl.: linked list with tail pointer



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q.enqueue(2)
```

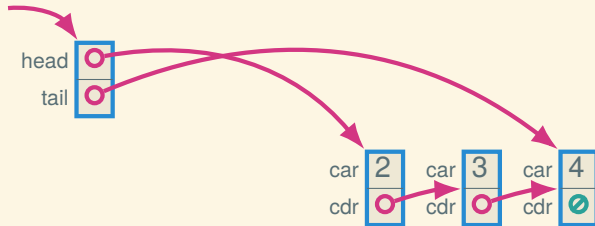
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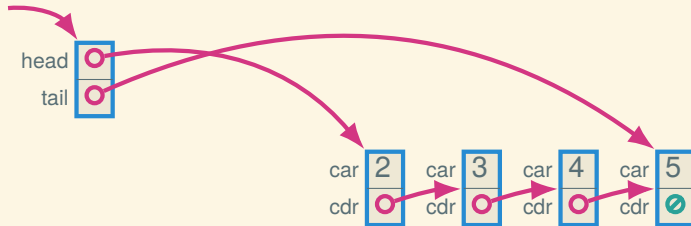


## Queue impl.: linked list with tail pointer



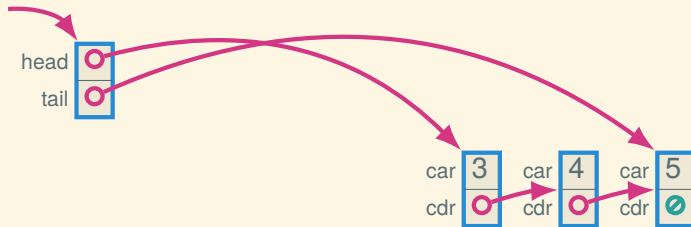
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let q = LinkedListQueue()  
q.enqueue(2)  
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q.enqueue(4)
```

## Queue impl.: linked list with tail pointer



```
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## Queue impl.: linked list with tail pointer



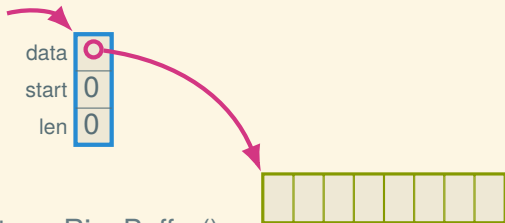
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## Queue impl.: linked list with tail pointer



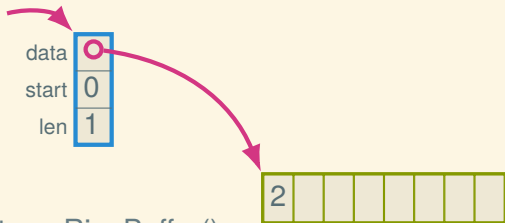
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```

# Queue implementation: ring buffer



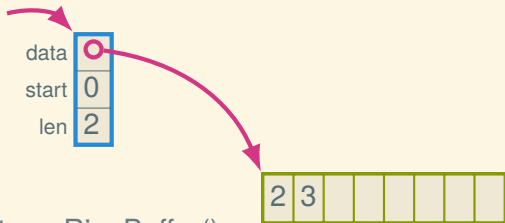
```
let q = RingBuffer()
```

# Queue implementation: ring buffer



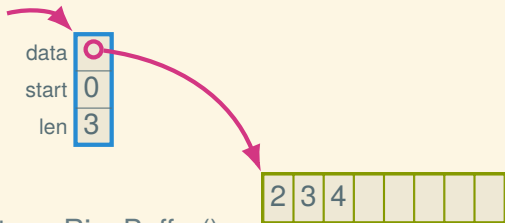
```
let q = RingBuffer()  
q.enqueue(2)
```

# Queue implementation: ring buffer



```
let q = RingBuffer()  
q.enqueue(2)  
q.enqueue(3)
```

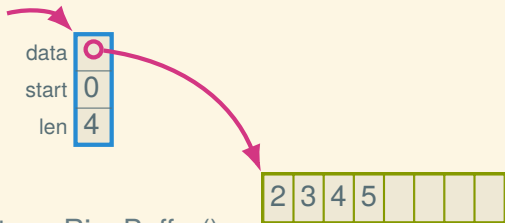
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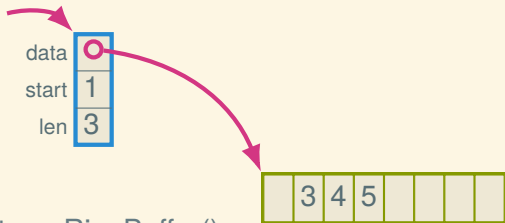


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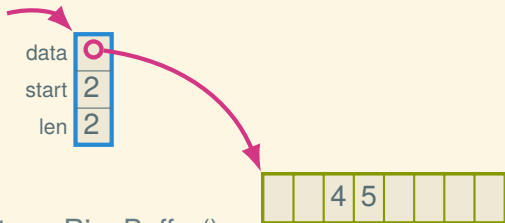
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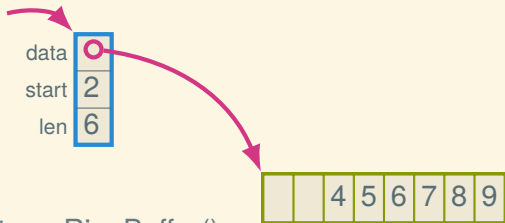
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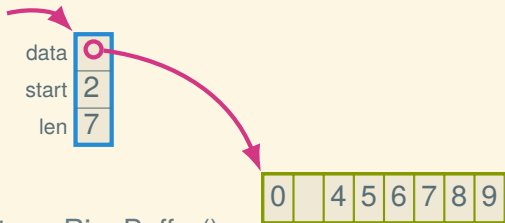
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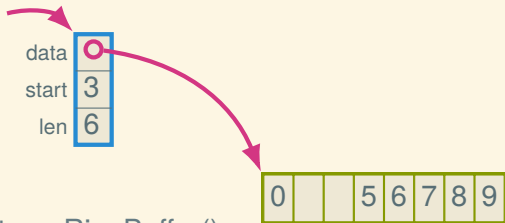
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q.enqueue(5)  
q.dequeue()  
q.dequeue()  
⋮
```

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```
let q = RingBuffer()  
q.enqueue(2)  
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q.dequeue()  
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⋮  
q.enqueue(0)
```

# Queue implementation: ring buffer



```
let q = RingBuffer()  
q.enqueue(2)  
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q.enqueue(4)  
q.enqueue(5)  
q.dequeue()  
q.dequeue()  
:  
q.enqueue(0)  
q.dequeue()
```

## Trade-offs: linked list queue versus ring buffer

Basically the same as for the stack implementations:

- Ring buffer has better constant factors and uses less space (potentially)
- Linked list doesn't fill up

## Ring buffer in DSSL2



## Signature, with full?

```
interface QUEUE[T]:  
  def enqueue(self, element: T) -> NoneC  
  def dequeue(self) -> T  
  def empty?(self) -> bool?  
  def full?(self) -> bool?
```

# Representation and initialization

```
class RingBuffer (QUEUE):  
    let data: VecC  
    let start: nat?  
    let size: nat?  
  
    def __init__(self, capacity):  
        self.data = [None; capacity]  
        self.start = 0  
        self.size = 0
```

...

## Size stuff

```
class RingBuffer (QUEUE):
  let data: VecC
  let start: nat?
  let size: nat?
  ...

  def cap(self):
    self.data.len()

  def len(self):
    self.size

  def empty?(self):
    self.len() == 0

  def full?(self):
    self.len() == self.cap()

  ...
```

# Enqueueing

```
class RingBuffer (QUEUE):
  let data: VecC
  let start: nat?
  let size: nat?
  ...

  def enqueue(me, value):
    if me.full?():
      error('RingBuffer.enqueue: full')
    let ix = (me.start + me.size) % me.cap()
    me.data[ix] = value
    me.size = me.size + 1

  ...
```

# Dequeuing

```
class RingBuffer (QUEUE):  
    let data: VecC  
    let start: nat?  
    let size: nat?  
    ...  
  
    def dequeue(me):  
        if me.empty?():  
            error('RingBuffer.dequeue: empty')  
        let result = me.data[me.start]  
        me.start = (me.start + 1) % me.cap()  
        me.size = me.size - 1  
        result  
  
    ...
```

## Dequeuing without Leaking

```
class RingBuffer (QUEUE):
  let data: VecC
  let start: nat?
  let size: nat?
  ...

  def dequeue(me):
    if me.empty?():
      error('RingBuffer.dequeue: empty')
    let result = me.data[me.start]
    me.data[me.start] = None
    me.start = (me.start + 1) % me.cap()
    me.size = me.size - 1
    result

  ...
```

Next time: BSTs and the Dictionary ADT