

HW 9 Solutions

Problem 6.14

a. $E[X^2(t)] = R(0) = 12 \text{ W}; E^2[X(t)] = \lim_{\tau \rightarrow \infty} R(\tau) = 9 \text{ W};$

$$\sigma_X^2 = E[X^2(t)] - E^2[X(t)] = 12 - 9 = 3 \text{ W.}$$

b. DC power $= E^2[X(t)] = 9 \text{ W.}$

c. Total power $= E[X^2(t)] = 12 \text{ W.}$

d. $S(f) = 9\delta(f) + 15 \text{sinc}^2(5f).$

Problem 6.15

a. The autocorrelation function is

$$\begin{aligned} R_X(\tau) &= E[Y(t)Y(t+\tau)] \\ &= E\{[X(t) + X(t-T)][X(t+\tau) + X(t+\tau-T)]\} \\ &= E[X(t)X(t+\tau)] + E[X(t)X(t+\tau+T)] \\ &\quad + E[X(t-T)X(t+\tau)] + E[X(t-T)X(t+\tau-T)] \\ &= 2R_X(\tau) + R_X(\tau-T) + R_X(\tau+T) \end{aligned}$$

b. Application of the time delay theorem of Fourier transforms gives

$$\begin{aligned} S_Y(f) &= 2S_X(f) + S_X(f)[\exp(-j2\pi fT) + \exp(j2\pi fT)] \\ &= 2S_X(f) + 2S_X(f)\cos(2\pi fT) \\ &= 4S_X(f)\cos^2(\pi fT) \end{aligned}$$

c. Use the transform pair

$$R_X(\tau) = \text{sinc}(\tau) \longleftrightarrow S_X(f) = \text{sinc}^2(f)$$

and the result of (b) to get

$$\begin{aligned} S_Y(f) &= 24 \text{sinc}^2(f) \cos^2(\pi f/4) \\ S_Y(f) &= 20 \text{sinc}^2(f) \cos^2(\frac{\pi f}{2}) \end{aligned}$$

Problem 6.23

- a. $E[Y(t)] = 0$ because the mean of the input is zero.
 b. The frequency response function of the filter is

$$H(f) = \frac{1}{10 + j2\pi f}$$

The output power spectrum is

$$\begin{aligned} S_Y(f) &= S_x(f) |H(f)|^2 \\ &= 1 \times \frac{1}{100 + (2\pi f)^2} \\ &= \frac{0.01}{1 + (2\pi f/10)^2} = 0.05 \times \frac{2/10}{1 + (2\pi f/10)^2} \end{aligned}$$

which is obtained applying (6.89).

- c. Use the transform pair $\exp(-|\tau|/\tau_0) \longleftrightarrow \frac{2\tau_0}{1 + (2\pi f\tau_0)^2}$ to find the power spectrum as

$$R_Y(\tau) = 0.05 e^{-10|\tau|}$$

- d. Since the input is Gaussian, so is the output. Also, $E[Y] = 0$ and $\text{var}[Y] = R_Y(0) = 0.05$, so

$$f_Y(y) = \frac{\exp(-y^2/2\sigma_Y^2)}{\sqrt{2\pi\sigma_Y^2}}$$

where $\sigma_Y^2 = 0.05$.

- e. Use (5.189) with

$$x = y_1 = Y(t_1), y = y_2 = Y(t_2), m_x = m_y = 0, \text{ and } \sigma_x^2 = \sigma_y^2 = 0.05$$

Also

$$\rho(\tau) = \frac{R_Y(\tau)}{R_Y(0)} = e^{-10|\tau|}$$

Set $\tau = 0.03$ to get $\rho(0.03) = 0.741$. Put these values into (5.189).

Problem 6.29

- a. Choosing $f_0 = f_1$ moves $-f_1$ right to $f = 0$ and f_1 left to $f = 0$. The lowpass filtered version of the superposition of these two spectra is the power spectrum of $n_c(t)$ or $n_s(t)$. It is a v-shaped spectrum centered at $f = 0$ given by $S_{LP}(f) = \frac{1}{2}N_0 \left[1 - \Lambda\left(\frac{f}{f_2 - f_1}\right) \right]$
- b. Choosing $f_0 = f_2$ moves $-f_2$ right to $f = 0$ and f_2 left to $f = 0$. Thus, the baseband spectrum can be written as $S_{LP}(f) = \frac{1}{2}N_0 \Lambda\left(\frac{f}{f_2 - f_1}\right)$.
- c. For this case both triangles (left and right) are centered around the origin and they add to give $S_{LP}(f) = \frac{1}{2}N_0 \Pi\left(\frac{f}{f_2 - f_1}\right)$.
- d. They are not uncorrelated for any case for an arbitrary delay. However, all cases give quadrature components that are uncorrelated at the same instant.

Problem 7.25

Solution: From the plot of the signal spectrum it is clear that:

$$k = \frac{A}{W^2}$$

Thus the signal power is: $S = 2 \int_0^W \frac{A}{W^2} f^2 df = \frac{2}{3} AW$

The noise power is $N_0 B$. This yields the signal-to-noise ratio:

$$(SNR)_1 = \frac{\frac{2}{3} AW}{N_0 B}$$

If B is reduced to W , the SNR becomes:

$$(SNR)_2 = \frac{\frac{2}{3} A}{N_0}$$

This increases the signal-to-noise ratio by a factor of $\frac{B}{W}$.

6. Solution: $y(t) = 2n(t) \cos(2\pi f_c t + \theta)$

$$= 2(n_c(t) \cos 2\pi f_c t - n_s(t) \sin 2\pi f_c t) \cos(2\pi f_c t + \theta)$$

$$= n_c(t) \cos \theta + n_c(t) \cos(4\pi f_c t + \theta) - n_s(t) \sin \theta - n_s(t) \sin(4\pi f_c t + \theta)$$

$$= y_{\text{lowpass}}(t) + y_{\text{bandpass}}(t)$$

$$\text{where } y_{\text{lowpass}}(t) = n_c(t) \cos \theta - n_s(t) \sin \theta$$

$$y_{\text{bandpass}}(t) = n_c(t) \cos(4\pi f_c t + \theta) - n_s(t) \sin(4\pi f_c t + \theta)$$

$$E[y_{\text{lp}}(t)] = E[n_c(t)] \cos \theta - E[n_s(t)] \sin \theta = E[n_w(t)] \cos \theta - E[n_w(t)] \sin \theta = 0$$

$$E[y_{\text{bp}}(t)] = E[n_c(t)] \cos(4\pi f_c t + \theta) - E[n_s(t)] \sin(4\pi f_c t + \theta) \quad (\text{assuming the noise has 0 mean})$$

$$E[y_{\text{lp}}^2(t)] = E[n_c^2(t)] \cos^2 \theta + E[n_s^2(t)] \sin^2 \theta - 2E[n_c(t) n_s(t)] \cos \theta \sin \theta$$

$$= E[n^2(t)] - 2E[n_c(t) n_s(t)] \cos \theta \sin \theta$$

= 0 if $\sin(4\pi f_c t)$ is symmetric around f_c

$$\text{Similarly, } E[y_{\text{bp}}^2(t)] = E[n^2(t)] - 2E[n_c(t) n_s(t)] \cos(4\pi f_c t + \theta) \sin(4\pi f_c t + \theta)$$

